

AMENDMENTS TO THE SPECIFICATION

IN THE SPECIFICATION:

Please add the following paragraph after the paragraph ending on page 3, line 25:

--Further scope of the applicability of the present invention will become apparent from the detailed description given hereinafter. However, it should be understood that the detailed description and specific examples, while indicating preferred embodiments of the invention, are given by way of illustration only, since various changes and modifications within the spirit and scope of the invention will become apparent to those skilled in the art from this detailed description.--

Please amend the paragraph beginning on page 6, line 23, as follows:

--Referring to FIG. 3B with accompanying FIG. 3A again, a detail of the shift device 14 is illustrated. A plurality of loaders 32 are provided on the conveyer to drive the shift device 14. The rotary disk 24 of the shift device 14 at the central portion thereof extends upward a central shaft 240. Each of the loaders 32 is preferably made of engineering plastics to avoid being worn out so as to maintain the accuracy thereof. The central shaft 240 at the upper end thereof is fixedly attached a

transmission gear 241 to mesh with the middle part of the loader 32 by way of a teeth part 242 thereof. As soon as the conveyer moves, the loader 32 can actuate the transmission gear 241 to rotate and cause the rotary disk 24 to rotate via the central shaft 240. As it has been mentioned previously, the periphery of the rotary disk 24 has a gear like shape so that there are receiving recesses 243 provided for receiving the bottle blanks respectively. Hence, the bottle blanks 23 received in the respective recess 243 are inserted by the support post 322 of one of the loaders 32 respectively such that the bottle blanks 23 are moved by the loaders 32 respectively as soon as the conveyer moves along with the loaders 32. In the mean time, the respective loader 32 carrying the respective bottle blank 23 can be sleeved into the respective bottle blank 23 while the bottle blanks 23 ~~inter-~~enter the positioning rail 15 and ascend along the guide surface 26. This is a design that each bottle blank 23 to be treated in the crystallizing machine 10 is corresponding to one of the loaders 32 on the conveyer and the conveyer and the shift mechanism 14 can be performed by a set of driving system instead of two sets of different driving systems. Therefore, the bottle blanks 23 can move with the loaders 32 synchronously to overcome the puzzle resulting from the need of adjusting the movement of the respective bottle blank 23 in accordance with the respective loader 32.--